## MTi-610

- Small, IP51-rated IMU
- Factory-calibrated inertial data
- Full Graphical User Interface (GUI) and Software Development Kit (SDK) available

The MTi-610 is a Inertial Measurement Unit with a small form-factor design for deep integration into your application. Building on the proven MTi 600-series technology it enables a robust and easy to use motion tracking. It is designed for easy integration and seamless interfacing with other equipment.

The MTi-610 is supported by the MT Software Suite which includes MT Manager (GUI for Windows/Linux), SDK, example codes and drivers for many platforms including ROS.



- White label and OEM integration options available
- 3D models available on request

Mechanical

• Available online via Digi-Key, Mouser, Farnell and local distributors

IMU performanceAccelerometerCalibratedGyroscopeCalibratedStrapdown Integration (SDI)YesGyroscopeStandard full range2000 deg/sIn-run bias stability8 deg/hBandwidth (-3dB)520 HzNoise Density0.007 ⁰/s/√Hzg-sensitivity (calibr.)0.1 ⁰/s/gAccelerometerStandard full range10 gIn-run bias stability10 (x,y) 15(z) μgBandwidth (-3dB)500 HzNoise Density60 μg/√Hz
Gyroscope Strapdown Integration (SDI)  Gyroscope  Standard full range In-run bias stability Bandwidth (-3dB) Noise Density g-sensitivity (calibr.)  Accelerometer  Standard full range In-run bias stability  Accelerometer  Standard full range In-run bias stability In (x,y) 15(z) μg  Bandwidth (-3dB) Soo Hz Noise Density Foo Hz Noise Density Noise Density Foo Hz Noise Density For Standard full range In for Standard full range In for Standard full range In for Standard full full full full full full full ful
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Magnetometer
Standard full range +/- 8 G
Total RMS noise — 1 mG
Non-linearity 0.2%
Resolution 0.25 mG
Barometer
Standard full range — 300-1250 hPa
Total RMS noise ————————————————————————————————————
Relative accuracy +/- 8 Pa (~0.5m)

Magnetometer		
Standard full range	+/- 8 G	
Total RMS noise	1 mG	
Non-linearity	0.2%	
Resolution	0.25 mG	
Barometer		
Standard full range	300-1250 hPa	
Total RMS noise	1.2 Pa	
Relative accuracy	+/- 8 Pa (~0.5m)	
Complete and detailed specifications are available at		
mtidocs.xsens.com		

IP-rating	IP51
Operating Temperature ———	-40 to 85 °C
Casing material	PC-ABS
Mounting orientation	No restriction, full 360° in all axes
Dimensions —	28x31.5x13 mm
Connector	Main: Phoenix Contact 16 pin, 1.27 mm
	pitch
Weight	8.9 g
Certifications	CE, FCC, RoHS

## **Electrical** Input voltage 4.5 to 24V Power consumption (typ) <0.5 W

Interfaces / 10	
Interfaces ———————	UART, CAN, RS232
Sync Options	SyncIn, SyncOut, ClockSync
Protocols	Xbus, ASCII (NMEA) or CAN
Clock drift	10 ppm (or external)
Output Frequency	Up to 2kHz, 400Hz SDI
Built-in-self test	Gyr, Acc, Mag, Baro

Software Suite	
GUI (Windows/Linux)	MT Manager, Firmware updater,
	Magnetic Field Mapper
SDK (Example code)	C++, C#, Python, Matlab, Nucleo,
	public source code
Drivers	LabVIEW, ROS, GO
Support	BASE by XSENS: online manuals,
	community and knowledge base



