

MLFB-Ordering data

6SL3220-1YE28-0UB0



Figure similar

Client order no. : Order no. : Offer no. : Remarks : Item no. :
Consignment no. :
Project :

Rated data			General tech. specifications	
Input			Power factor λ	0.70 0.85
Number of phases	3 AC		Offset factor cos φ	0.96
Line voltage	380 480 V +10 % -20 %		Efficiency η	0.98
Line frequency	47 63 Hz		Sound pressure level (1m)	67 dB
Rated voltage	400V IEC	480V NEC	Power loss	0.396 kW
Rated current (LO)	29.50 A	29.50 A	Filter class (integrated)	Unfiltered
Rated current (HO)	23.97 A	24.50 A		
Output			EMC category (with accessories)	without
Number of phases	3 AC			
Rated voltage	400V IEC	480V NEC	Ambient conditions	
Rated power (LO)	15.00 kW	20.00 hp	Standard board coating type	Class 3C2, according to IEC 60721-3-3: 2002
Rated power (HO)	11.00 kW	15.00 hp		
Rated current (LO)	32.00 A	27.00 A	Cooling	Air cooling using an integrated fan
Rated current (HO)	26.00 A	21.00 A		
Rated current (IN)	33.00 A		Cooling air requirement	0.018 m³/s (0.653 ft³/s)
Max. output current	43.00 A		Installation altitude	1000 m (3280.84 ft)
Pulse frequency	4 kHz		Ambient temperature	
Output frequency for vector control	0 200 Hz		Operation	-20 45 °C (-4 113 °F)
			Transport	-40 70 °C (-40 158 °F)
Output frequency for V/f control	0 550 Hz		Storage	-25 55 °C (-13 131 °F)
			Relative humidity	
			Max. operation	95 % At 40 °C (104 °F), condensation and icing not permissible

Overload capability

Low Overload (LO)

110% base load current IL for 60 s in a 300 s cycle time

High Overload (HO)

150% x base load current IH for 60 s within a 600 s cycle time



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Figure simila

Mechanical data		Closed-loop co	ntrol techniques	
Degree of protection IP20 / UL open type		Closed-loop co	ntioi teciniques	
	, ,,	V/f linear / square-law / parameter	rizable Yes	
Size	FSC	V/f with flux current control (FCC)	Yes	
Net weight	7 kg (15.74 lb)	V/f ECO linear / square-law	Yes	
Width	140 mm (5.51 in)	Sensorless vector control	Yes	
Height	295 mm (11.61 in)	Vector control, with sensor	No	
Depth	218 mm (8.58 in)	— Encoderless torque control	Yes	
Inputs / outputs		Encoderiess torque control	TC3	
Standard digital inputs		Torque control, with encoder	No	
Number	6	Commi	unication	
Switching level: 0→1	11 V			
Switching level: 1→0	5 V	Communication	USS, Modbus RTU, BACnet MS/TP	
Max. inrush current	15 mA	Connections		
Fail-safe digital inputs		Signal cable		
Number	1	Conductor cross-section	0.15 1.50 mm ² (AWG 24 AWG 16)	
Digital outputs		Line side		
Number as relay changeover contact	2	Version	screw-type terminal	
Output (resistive load)	DC 30 V, 5.0 A	Conductor cross-section	1.50 16.00 mm ² (AWG 16 AWG 6)	
Number as transistor	0	Motor end		
Analog / digital inputs		Version	Screw-type terminals	
Number	2 (Differential input)	Conductor cross-section	1.50 16.00 mm ² (AWG 16 AWG 6)	
Resolution	10 bit	DC link (for braking resistor)	(10)	
Switching threshold as digital input		PE connection	On housing with M4 screw	
0→1	4 V	Max. motor cable length	on nousing with wir screw	
1→0	1.6 V	Shielded	150 m (492.13 ft)	
Analog outputs		Unshielded	300 m (984.25 ft)	
Number	1 (Non-isolated output)	onsinewed	500 III (504.25 IU)	
PTC/ KTY interface				

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy $\pm 5~^{\circ}\text{C}$



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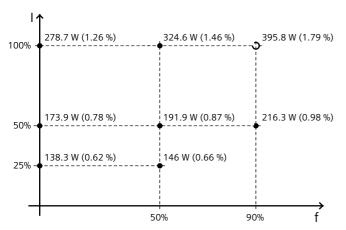
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Figure similar

Converter losses to EN 50598-2*

Efficiency class	IE2
Comparison with the reference converter (90% / 100%)	-35.40 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

Standards

Compliance with standards UL, cUL, CE, C-Tick (RCM), EAC, KCC, SEMI F47, REACH

CE marking

EMC Directive 2004/108/EC, Low-Voltage Directive 2006/95/EC

^{*}converted values