

X-LSM-E Series Datasheet



- 25, 50, 100, 150, 200 mm travel
- Up to 104 mm/s speed and up to 55 N thrust
- Recirculating ball bearing design for high load (25 kg) and long lifetime
- Built-in controller; daisy-chains with other Zaber products
- Integrated, 200 CPR, motor mounted encoder provides slip/stall detection and recovery
- Custom versions available

X-LSM-E Series Overview

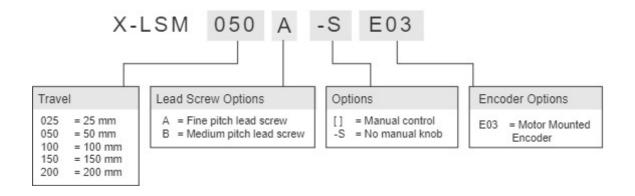
Zaber's X-LSM-E Series devices are computer-controlled, motorized linear stages with high thrust and speed capabilities and a compact size. They are stand-alone units requiring only a standard 24 V or 48 V power supply. The built-in motor encoder allows closed-loop operation and slip/stall recovery features. An optional indexed knob provides convenient manual control for versatile operation even without a computer.

These stages connect to the RS-232 port or USB port of any computer, and they can be daisy-chained with any other Zaber products. The daisy-chain also shares power, making it possible for multiple X-Series products to share a single power supply. Convenient locking, 4-pin, M8 connectors on the unit allow for secure connection between units.

At only 21 mm high, these miniature stages are excellent for applications where a small profile is required. The X-LSM-E's innovative design allows speeds up to 104 mm/s and loads up to 25 kg. Like all of Zaber's products, the X-LSM-E Series is designed to be 'plug and play' and very easy to set up and operate. If you are considering a multi-axis system, in the XY configuration, these stages make excellent microscope stages. Adding an X-JOY3 joystick controller allows manual control of both X and Y or XYZ axes from a single interface as well as allowing microscope stage positions to be saved and recalled at the touch of a button.

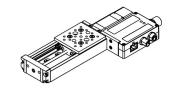
For more information visit: https://www.zaber.comproducts/linear-stages/X-LSM-E

X-LSM-E Series Part Numbering



X-LSM-E Series Drawings

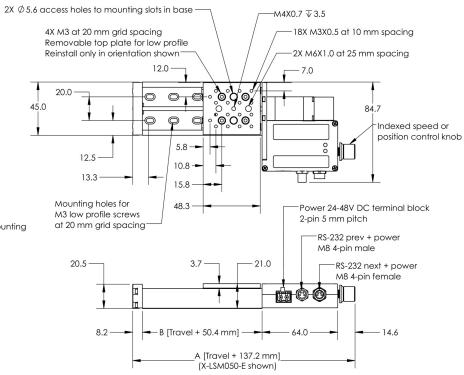
ZABER x-LSM-E Miniature Motorized Linear Stage dimensions in mm

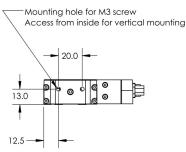


Model Number*	Travel	A **	В
X-LSM025	25.4	162.6	75.8
X-LSM050	50.8	188.0	101.2
X-LSM100	101.6	238.8	152.0
X-LSM150	152.4	289.6	202.8
X-LSM200	203.2	340.4	253.6

^{*}See product page for complete list of available models at www.zaber.com

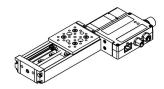
^{**}Subtract 13.1 mm knob length from 'A' for -S versions without manual control





DWG 3429 R01

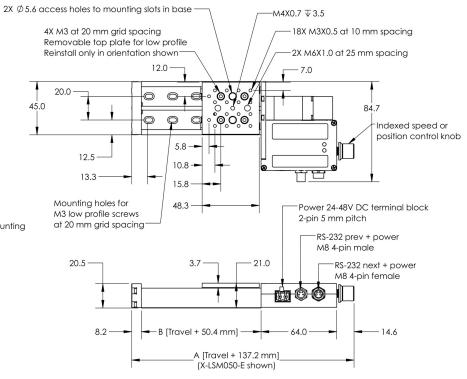


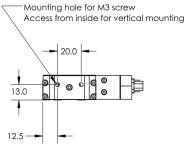


Model Number*	Travel	A **	В
X-LSM025	25.4	162.6	75.8
X-LSM050	50.8	188.0	101.2
X-LSM100	101.6	238.8	152.0
X-LSM150	152.4	289.6	202.8
X-LSM200	203.2	340.4	253.6

*See product page for complete list of available models at www.zaber.com

**Subtract 13.1 mm knob length from 'A' for -S versions without manual control





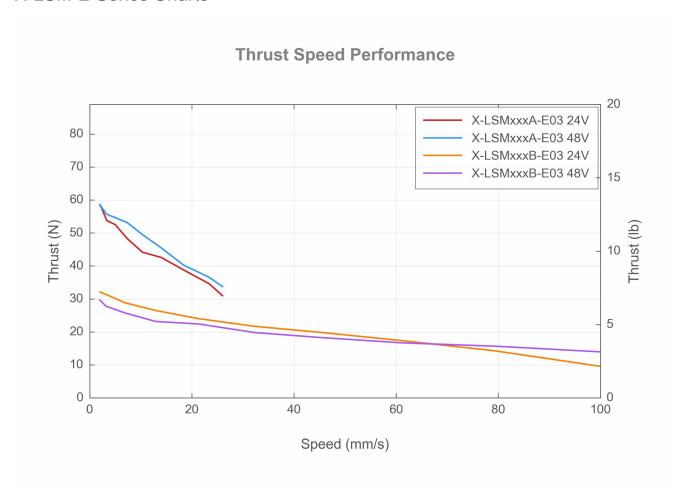
DWG 3429 R01

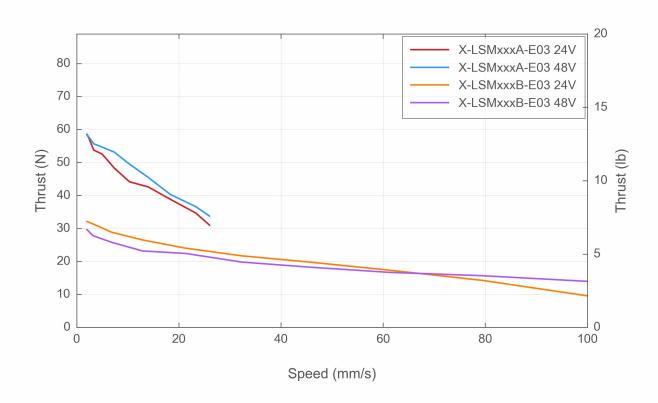
X-LSM-E Series Specifications

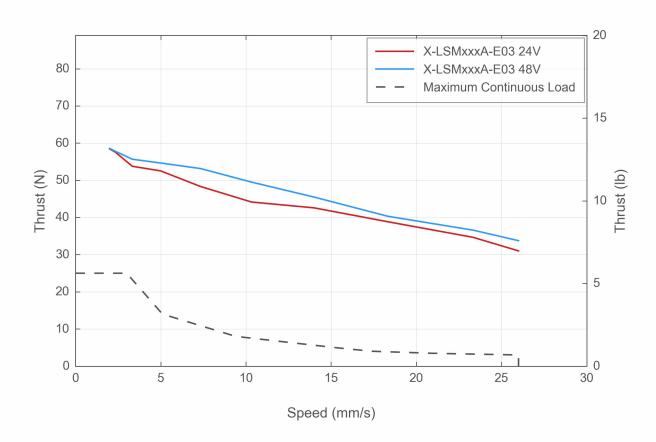
Microstep Size (Default Resolution) 0.0 Built-in Controller Ye	alue	Altamata IInit
Built-in Controller Ye	047005	Alternate Unit
	.047625 μm	
Travel Range 10	es	
	01.6 mm	4.000"
Accuracy (unidirectional) 35	5 μm	0.001378"
Repeatability < 3	3 µm	< 0.000118"
Backlash <	12 μm	< 0.000472"
Maximum Speed 26	6 mm/s	1.024"/s
Minimum Speed 0.0	.000029 mm/s	0.000001"/s
Speed Resolution 0.0	.000029 mm/s	0.000001"/s
Encoder Resolution 20	00 CPR	800 states/rev
Encoder Type Ro	otary quadrature encoder	
Peak Thrust 55	5 N	12.3 lb
Maximum Continuous Thrust 25	5 N	5.6 lb
Communication Interface RS	S-232	
Communication Protocol Za	aber ASCII (Default), Zaber Binary	
Maximum Centered Load 25	50 N	56.1 lb
Maximum Cantilever Load 10	0 N-m	7.4 ft-lb
Guide Type Re	ecirculating ball bearing	
Vertical Runout <	18 μm	< 0.000709"
Horizontal Runout <	18 μm	< 0.000709"
	.04°	0.698 mrad
Pitch 0.0		
	.04°	0.698 mrad
Roll 0.0	.04° .04°	0.698 mrad 0.698 mrad
Roll 0.0 Yaw 0.0		
Roll 0.0 Yaw 0.0 Stiffness in Pitch 15	.04°	0.698 mrad
Roll 0.0 Yaw 0.0 Stiffness in Pitch 15 Stiffness in Roll 15	.04° 50 N-m/°	0.698 mrad 116 μrad/N-m
Roll 0.0 Yaw 0.0 Stiffness in Pitch 15 Stiffness in Roll 15 Stiffness in Yaw 15	.04° 50 N-m/° 50 N-m/°	0.698 mrad 116 μrad/N-m 116 μrad/N-m
Roll 0.0 Yaw 0.0 Stiffness in Pitch 15 Stiffness in Roll 15 Stiffness in Yaw 15 Maximum Current Draw 35	.04° 50 N-m/° 50 N-m/°	0.698 mrad 116 μrad/N-m 116 μrad/N-m
Roll 0.0 Yaw 0.0 Stiffness in Pitch 15 Stiffness in Roll 15 Stiffness in Yaw 15 Maximum Current Draw 35 Power Supply 24	.04° 50 N-m/° 50 N-m/° 50 N-m/°	0.698 mrad 116 μrad/N-m 116 μrad/N-m

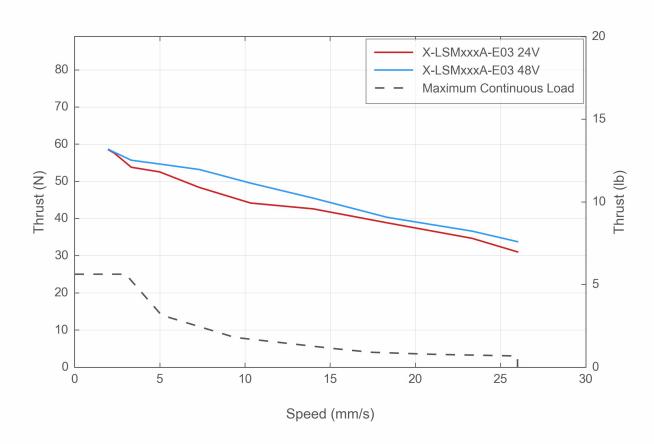
Specification	Value	Alternate Unit
Motor Steps Per Rev	200	
Motor Type	Stepper (2 phase)	
Motor Rated Current	600 mA/phase	
Inductance	3.5 mH/phase	
Default Resolution	1/64 of a step	
Data Cable Connection	Locking 4-pin M8	
Mechanical Drive System	Precision lead screw	
Limit or Home Sensing	Magnetic hall sensor	
Manual Control	Yes	
Axes of Motion	1	
LED Indicators	Yes	
Mounting Interface	M3 and M6 threaded holes and M4 threaded centre hole	
Operating Temperature Range	0 to 50 °C	
Vacuum Compatible	No	
RoHS Compliant	Yes	
Stage Parallelism	< 25 µm	< 0.000984"
CE Compliant	Yes	
Weight	0.39 kg	0.860 lb

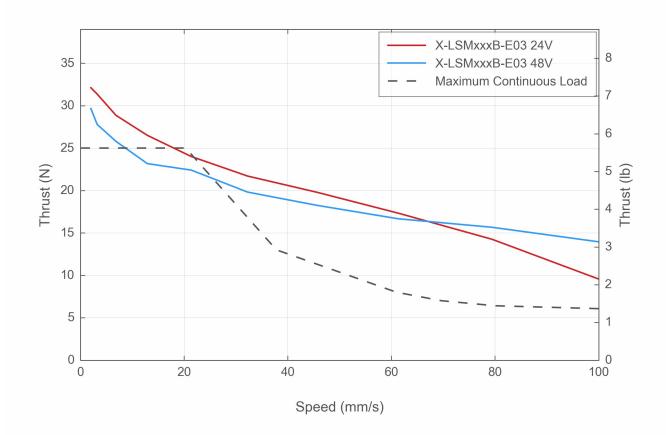
X-LSM-E Series Charts

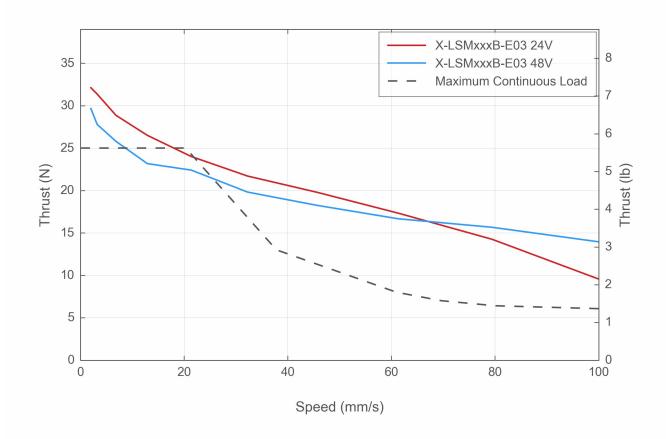




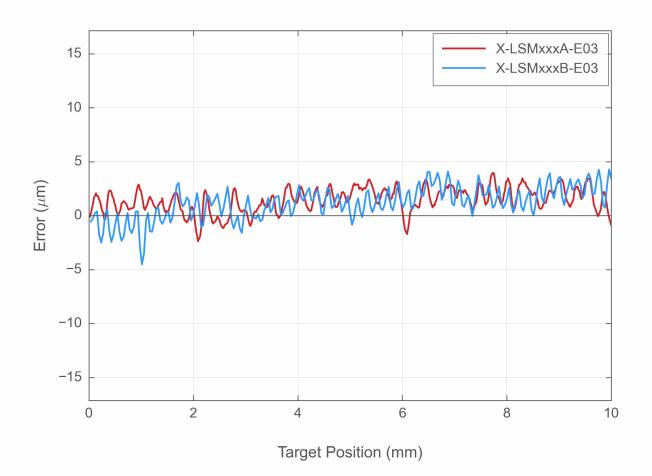




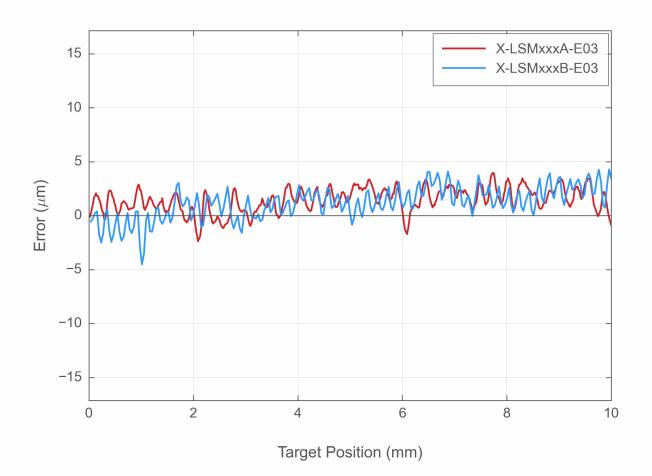




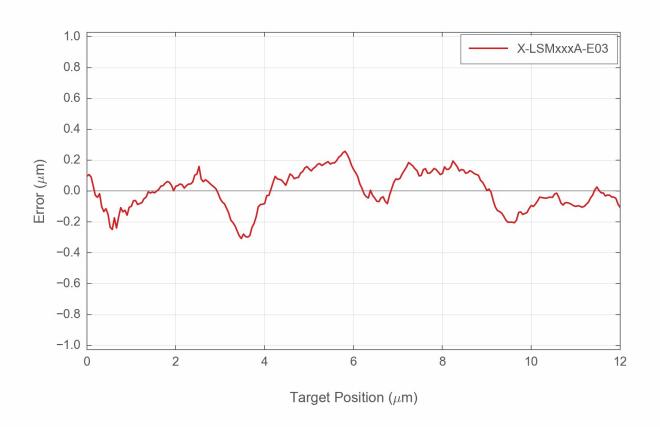
Typical Accuracy



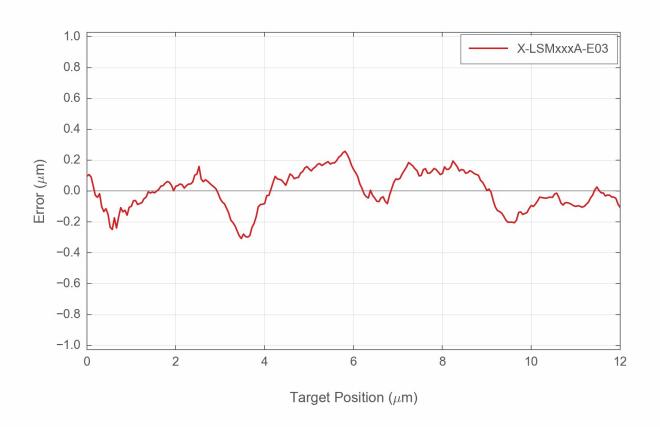
Typical Accuracy



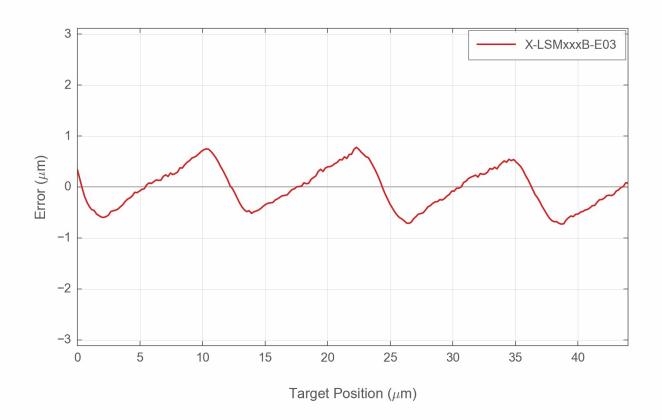




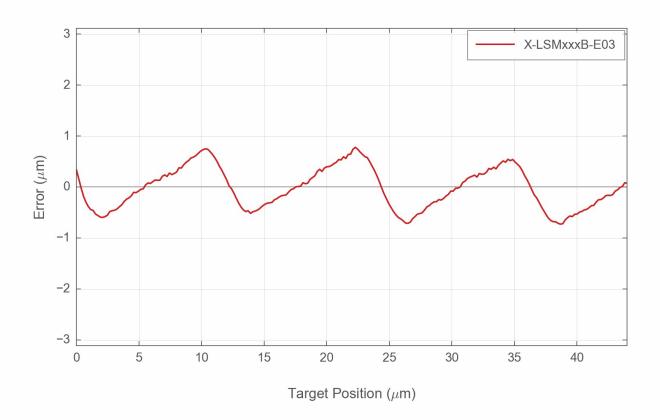




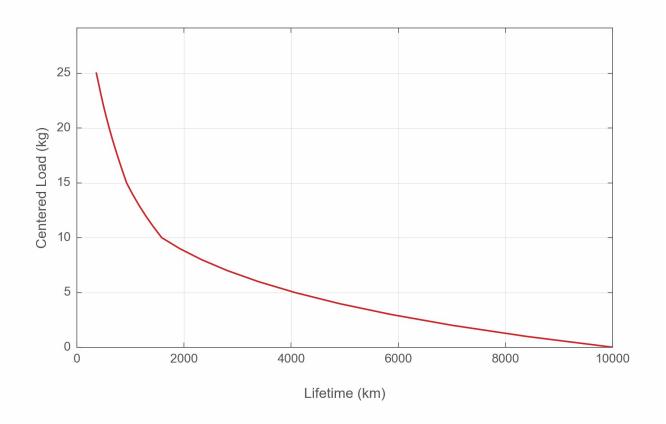
Typical Microstepping Accuracy

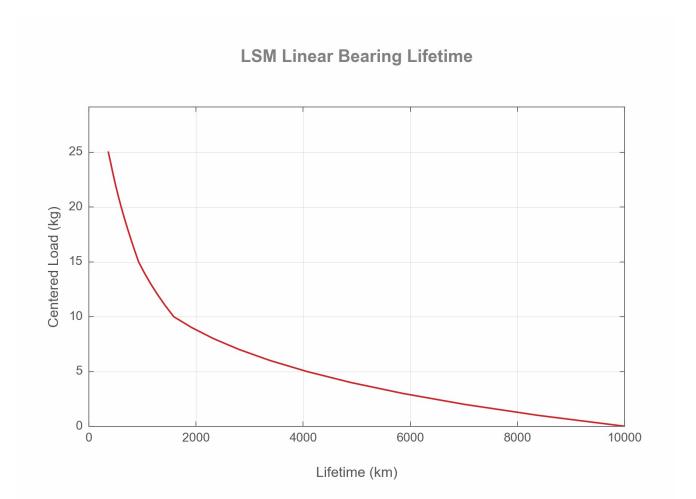


Typical Microstepping Accuracy



LSM Linear Bearing Lifetime





Contact

Email: contact@zaber.com

Phone (toll free Canada/USA): 1-888-276-8033

Phone (direct): 1-604-569-3780

Fax: 1-604-648-8033

Zaber Technologies Inc.

#2 - 605 West Kent Ave. N.

Vancouver, British Columbia

Canada, V6P 6T7

https://www.zaber.com