## **MTi-680G**

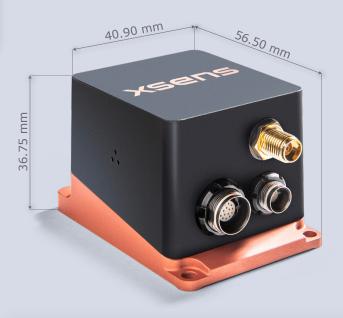
- Rugged, IP68 rated RTK GNSS/INS
- 0.2 deg roll/pitch & cm-level position accuracy
- Internal u-blox ZED F9 RTK enabled GNSS receiver

The MTi-680G is an RTK enabled GNSS/INS with a ruggedized housing featuring IP68 protection against environmental influences. Building on the proven MTi 600-series technology it enables a robust and easy to use cm-level positioning and orientation tracking for outdoor applications. It features a powerful onboard u-blox ZED F9 RTK GNSS receiver to provide superior positioning performance. It is designed for easy integration and seamless interfacing with other equipment.

The MTi-680G is supported by the MT Software Suite which includes MT Manager (GUI for Windows/Linux), SDK, example codes and drivers for many platforms including ROS.

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ensor Fusion Performance		Barometer	
oll, Pitch	0,2 deg RMS	Standard full range	300-125
aw/Heading	0.5 deg RMS	Total RMS noise	1.2 Pa
osition	1cm+1ppm CEP <sup>1</sup>	Relative accuracy	
elocity	0.05m/s RMS	Mechanical	
iyroscope		IP-rating	IP68
tandard full range	2000 deg/s	Operating Temperature	-40 to 8
n-run bias stability	8 deg/h	Casing material	Aluminu
andwidth (-3dB)	520 Hz	Mounting orientation	No restr
oise Density	0.007 º/s/√Hz	Dimensions	56.50x4
-sensitivity (calibr.)	0.1 °/s/g	Connector	Main: Ol
ccelerometer			RTCM: C
tandard full range	10 g		Antenna
n-run bias stability	10 (x,y) 15(z) µg	Weight	98 g
andwidth (-3dB)	500 Hz	Certifications	CE, FCC
oise Density	60 µg/√Hz	Interfaces / IO	
lagnetometer		Interfaces	CAN, RS
tandard full range	+/- 8 G	Sync Options	SyncIn,
otal RMS noise	1 mG	Protocols	Xbus, As
on-linearity	0.2%	Clock drift	1ppm
esolution	0.25 mG	Output Frequency	Up to 2k
TK GNSS Receiver		Built-in-self test	Gyro, Ac
rand	u-blox	Software Suite	
odel	ZED F9	GUI (Windows/Linux)	MT Mana
TK correction input	RTCM 3.2/3.3		Magneti
TCM input port	RS232 (38K4-921K6 bit/s)	SDK (Example code)	C++, C#
	K3232 (30K4 921K6 bi(3)		public so
lectrical		Drivers	LabVIEV
nput voltage	4.5 to 24V	Support	BASE by
ower consumption (typ)	<1 W 1 Depending on GNSS conditions		commur



- White label and OEM integration options available
- 3D models available on request

• Available online via Digi-Key, Mouser, Farnell and local distributors

Complete and detailed specifications are available at mtidocs.xsens.com

	Barometer			
	Standard full range	300-1250 hPa		
	Total RMS noise	1.2 Pa		
<b>D</b> <sup>1</sup>	Relative accuracy	+/- 8 Pa (~0.5m)		
	Mechanical			
	IP-rating	IP68		
	Operating Temperature	-40 to 85 °C		
	Casing material	Aluminum		
	Mounting orientation	No restriction, full 360° in all axes		
	Dimensions	56.50x40.90x36.75 mm		
	Connector	Main: ODU (AMC HD 12 pins)		
		RTCM: ODU (AMC HD 4 pins)		
		Antenna: SMA		
g	Weight	98 g		
	Certifications	CE, FCC, RoHS		
	Interfaces / IO			
	Interfaces	CAN, RS232		
	Sync Options	SyncIn, SyncOut, ClockSync		
	Protocols	Xbus, ASCII (NMEA) or CAN		
	Clock drift	1ppm		
	Output Frequency	Up to 2kHz, 400 Hz SDI		
	Built-in-self test	Gyro, Acc, Mag, Baro, GNSS		
	Software Suite			
	GUI (Windows/Linux)	MT Manager, Firmware updater,		
		Magnetic Field Mapper		
21K6 bit/s)	SDK (Example code)	C++, C#, Python, Matlab, Nucleo,		
. ,		public source code		
	Drivers	LabVIEW, ROS, GO		
	Support	BASE by XSENS: online manuals,		
on GNSS conditions		community and knowledge base		



