

## RTC Module With 512Kx8 NVSRAM

### Features

- Integrated SRAM, real-time clock, crystal, power-fail control circuit, and battery
- Real-Time Clock counts seconds through years in BCD format
- RAM-like clock access
- Pin-compatible with industry-standard 512K x 8 SRAMs
- Unlimited write cycles
- 10-year minimum data retention and clock operation in the absence of power
- Automatic power-fail chip deselect and write-protection
- Software clock calibration for greater than ±1 minute per month accuracy

### General Description

The bq4850Y RTC Module is a non-volatile 4,194,304-bit SRAM organized as 524,288 words by 8 bits with an integral accessible real-time clock.

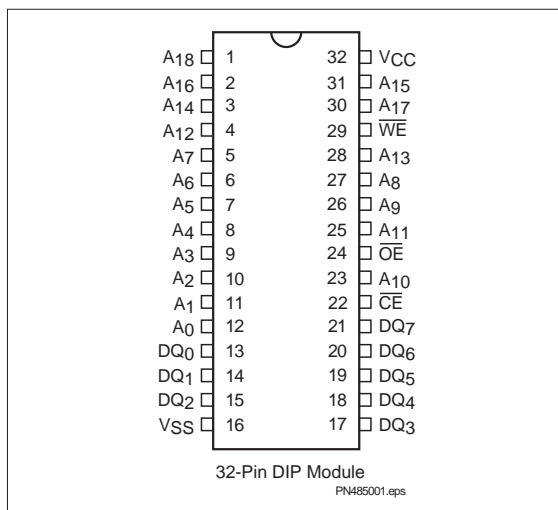
The device combines an internal lithium battery, quartz crystal, clock and power-fail chip, and a full CMOS SRAM in a plastic 32-pin DIP module. The RTC Module directly replaces industry-standard SRAMs and also fits into many EPROM and EEPROM sockets without any requirement for special write timing or limitations on the number of write cycles.

Registers for the real-time clock, alarm and other special functions are located in registers 7FFF8h–7FFFFh of the memory array.

The clock and alarm registers are dual-port read/write SRAM locations that are updated once per second by a clock control circuit from the internal clock counters. The dual-port registers allow clock updates to occur without interrupting normal access to the rest of the SRAM array.

The bq4850Y also contains a power-fail-detect circuit. The circuit deselects the device whenever  $V_{CC}$  falls below tolerance, providing a high degree of data security. The battery is electrically isolated when shipped from the factory to provide maximum battery capacity. The battery remains disconnected until the first application of  $V_{CC}$ .

### Pin Connections



### Pin Names

A0–A18	Address input
$\overline{CE}$	Chip enable
$\overline{WE}$	Write enable
$\overline{OE}$	Output enable
DQ0–DQ7	Data in/data out
$V_{CC}$	+5 volts
$V_{SS}$	Ground

# bq4850Y

## Functional Description

including memory and clock interface, and data-retention modes.

Figure 1 is a block diagram of the bq4850Y. The following sections describe the bq4850Y functional operation,

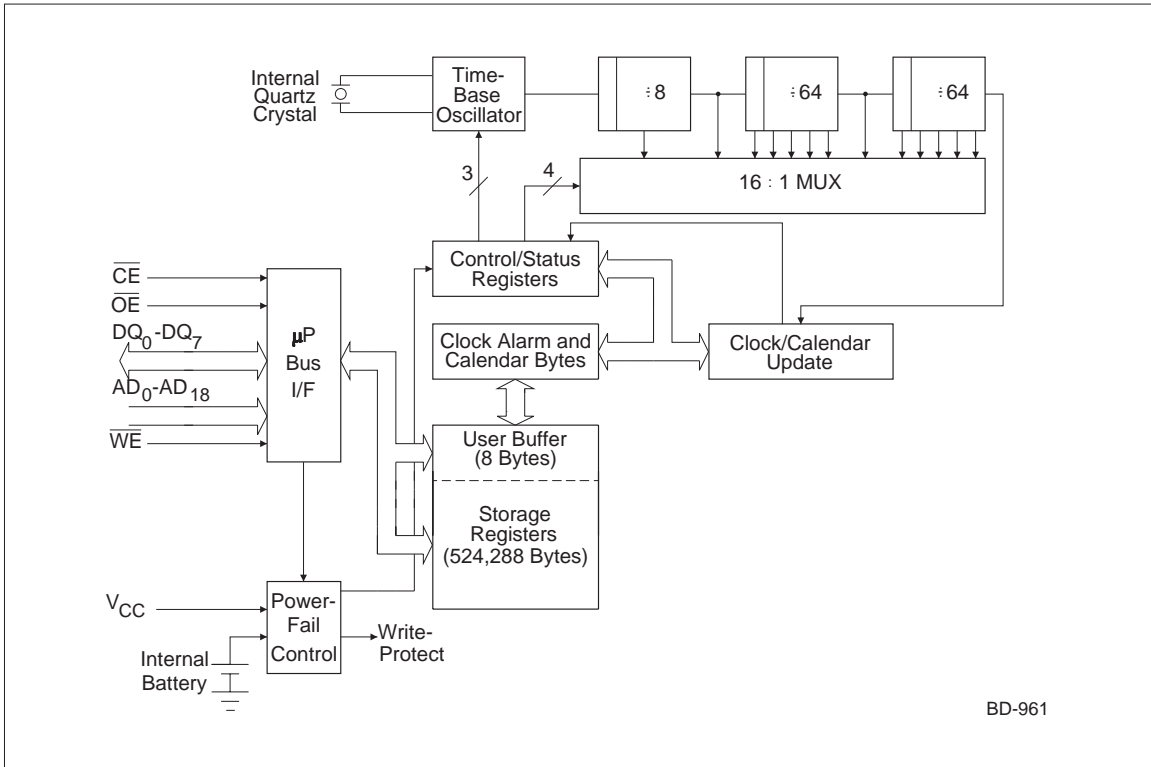


Figure 1. Block Diagram

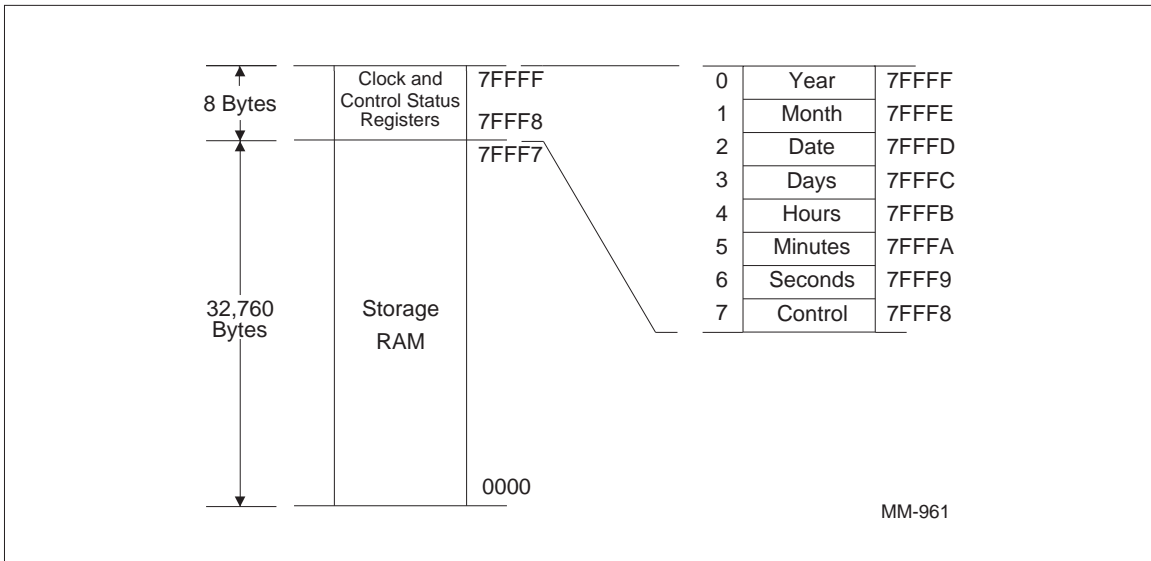
## Truth Table

V <sub>CC</sub>	$\overline{\text{CE}}$	$\overline{\text{OE}}$	$\overline{\text{WE}}$	Mode	DQ	Power
< V <sub>CC</sub> (max.)	V <sub>IH</sub>	X	X	Deselect	High Z	Standby
	V <sub>IL</sub>	X	V <sub>IL</sub>	Write	D <sub>IN</sub>	Active
> V <sub>CC</sub> (min.)	V <sub>IL</sub>	V <sub>IL</sub>	V <sub>IH</sub>	Read	D <sub>OUT</sub>	Active
	V <sub>IL</sub>	V <sub>IH</sub>	V <sub>IH</sub>	Read	High Z	Active
< V <sub>PF<sub>D</sub></sub> (min.) > V <sub>SO</sub>	X	X	X	Deselect	High Z	CMOS standby
≤ V <sub>SO</sub>	X	X	X	Deselect	High Z	Battery-backup mode

**Address Map**

The bq4850Y provides 8 bytes of clock and control status registers and 524,288 bytes of storage RAM.

Figure 2 illustrates the address map for the bq4850Y. Table 1 is a map of the bq4850Y registers.



**Figure 2. Address Map**

**Table 1. bq4850Y Clock and Control Register Map**

Address	D7	D6	D5	D4	D3	D2	D1	D0	Range (h)	Register
7FFFF	10 Years				Year				00-99	Year
7FFF8	X	X	X	10 Month	Month				01-12	Month
7FFF7	X	X	10 Date		Date				01-31	Date
7FFF6	X	FTE	X	X	X	Day			01-07	Days
7FFF5	X	X	10 Hours		Hours				00-23	Hours
7FFF4	X	10 Minutes			Minutes				00-59	Minutes
7FFF3	OSC	10 Seconds			Seconds				00-59	Seconds
7FFF2	W	R	S	Calibration				00-31	Control	

**Notes:** X = Unused bits; can be written and read.  
 Clock/Calendar data in 24-hour BCD format.  
 OSC = 1 stops the clock oscillator.

# bq4850Y

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## Memory Interface

### Read Mode

The bq4850Y is in read mode whenever  $\overline{OE}$  (output enable) is low and  $\overline{CE}$  (chip enable) is low. The device architecture allows ripple-through access of data from eight of 4,194,304 locations in the static storage array. Thus, the unique address specified by the 19 address inputs defines which one of the 524,288 bytes of data is to be accessed. Valid data is available at the data I/O pins within  $t_{AA}$  (address access time) after the last address input signal is stable, providing that the  $\overline{CE}$  and  $\overline{OE}$  (output enable) access times are also satisfied. If the  $\overline{CE}$  and  $\overline{OE}$  access times are not met, valid data is available after the latter of chip enable access time ( $t_{ACE}$ ) or output enable access time ( $t_{OE}$ ).

$\overline{CE}$  and  $\overline{OE}$  control the state of the eight three-state data I/O signals. If the outputs are activated before  $t_{AA}$ , the data lines are driven to an indeterminate state until  $t_{AA}$ . If the address inputs are changed while  $\overline{CE}$  and  $\overline{OE}$  remain low, output data remains valid for  $t_{OH}$  (output data hold time), but goes indeterminate until the next address access.

### Write Mode

The bq4850Y is in write mode whenever  $\overline{WE}$  and  $\overline{CE}$  are active. The start of a write is referenced from the latter-occurring falling edge of  $\overline{WE}$  or  $\overline{CE}$ . A write is terminated by the earlier rising edge of  $\overline{WE}$  or  $\overline{CE}$ . The addresses must be held valid throughout the cycle.  $\overline{CE}$  or  $\overline{WE}$  must return high for a minimum of  $t_{WR2}$  from  $\overline{CE}$  or  $t_{WR1}$  from  $\overline{WE}$  prior to the initiation of another read or write cycle.

Data-in must be valid  $t_{DW}$  prior to the end of write and remain valid for  $t_{DH1}$  or  $t_{DH2}$  afterward.  $\overline{OE}$  should be kept high during write cycles to avoid bus contention; although, if the output bus has been activated by a low on  $\overline{CE}$  and  $\overline{OE}$ , a low on  $\overline{WE}$  disables the outputs  $t_{WZ}$  after  $\overline{WE}$  falls.

### Data-Retention Mode

With valid  $V_{CC}$  applied, the bq4850Y operates as a conventional static RAM. Should the supply voltage decay, the RAM automatically power-fail deselects, write-protecting itself  $t_{WPT}$  after  $V_{CC}$  falls below  $V_{PFD}$ . All outputs become high impedance, and all inputs are treated as "don't care."

If power-fail detection occurs during a valid access, the memory cycle continues to completion. If the memory cycle fails to terminate within time  $t_{WPT}$ , write-protection takes place. When  $V_{CC}$  drops below  $V_{SO}$ , the control circuit switches power to the internal energy source, which preserves data.

The internal coin cell maintains data in the bq4850Y after the initial application of  $V_{CC}$  for an accumulated period of at least 10 years when  $V_{CC}$  is less than  $V_{SO}$ . As system power returns and  $V_{CC}$  rises above  $V_{SO}$ , the battery is disconnected, and the power supply is switched to external  $V_{CC}$ . Write-protection continues for  $t_{CER}$  after  $V_{CC}$  reaches  $V_{PFD}$  to allow for processor stabilization. After  $t_{CER}$ , normal RAM operation can resume.

## Clock Interface

### Reading the Clock

The interface to the clock and control registers of the bq4850Y is the same as that for the general-purpose storage memory. Once every second, the user-accessible clock/calendar locations are updated simultaneously from the internal real time counters. To prevent reading data in transition, updates to the bq4850Y clock registers should be halted. Updating is halted by setting the read bit D6 of the control register to 1. As long as the read bit is 1, updates to user-accessible clock locations are inhibited. Once the frozen clock information is retrieved by reading the appropriate clock memory locations, the read bit should be reset to 0 in order to allow updates to occur from the internal counters. Because the internal counters are not halted by setting the read bit, reading the clock locations has no effect on clock accuracy. Once the read bit is reset to 0, within one second the internal registers update the user-accessible registers with the correct time. A halt command issued during a clock update allows the update to occur before freezing the data.

### Setting the Clock

Bit D7 of the control register is the write bit. Like the read bit, the write bit when set to a 1 halts updates to the clock/calendar memory locations. Once frozen, the locations can be written with the desired information in 24-hour BCD format. Resetting the write bit to 0 causes the written values to be transferred to the internal clock counters and allows updates to the user-accessible registers to resume within one second. Use the write bit, D7, only when updating the time registers (7FFFF-7FFF9).

### Stopping and Starting the Clock Oscillator

The OSC bit in the seconds register turns the clock on or off. If the bq4850Y is to spend a significant period of time in storage, the clock oscillator can be turned off to preserve battery capacity. OSC set to 1 stops the clock oscillator. When OSC is reset to 0, the clock oscillator is turned on and clock updates to user-accessible memory locations occur within one second.

The OSC bit is set to 1 when shipped from the Benchmark factory.

### Calibrating the Clock

The bq4850Y real-time clock is driven by a quartz controlled oscillator with a nominal frequency of 32,768 Hz. The quartz crystal is contained within the bq4850Y package along with the battery. The clock accuracy of the bq4850Y module is tested to be within 20ppm or about 1 minute per month at 25°C. The oscillation rates of crystals change with temperature as Figure 3 shows. To compensate for the frequency shift, the bq4850Y offers onboard software clock calibration. The user can adjust the calibration based on the typical operating temperature of individual applications.

The software calibration bits are located in the control register. Bits D0–D4 control the magnitude of correction, and bit D5 the direction (positive or negative) of correction. Assuming that the oscillator is running at exactly 32,786 Hz, each calibration step of D0–D4 adjusts the clock rate by +4.068 ppm (+10.7 seconds per month) or -2.034 ppm (-5.35 seconds per month) depending on the value of the sign bit D5. When the sign bit is 1, positive adjustment occurs; a 0 activates negative adjustment. The total range of clock calibration is +5.5 or -2.75 minutes per month.

Two methods can be used to ascertain how much calibration a given bq4850Y may require in a system. The first involves simply setting the clock, letting it run for a month, and then comparing the time to an accurate known reference like WWV radio broadcasts. Based on the variation to the standard, the end user can adjust the clock to match the system's environment even after the product is packaged in a non-serviceable enclosure. The only requirement is a utility that allows the end user to access the calibration bits in the control register.

The second approach uses a bq4850Y test mode. When the frequency test mode enable bit FTE in the days reg-

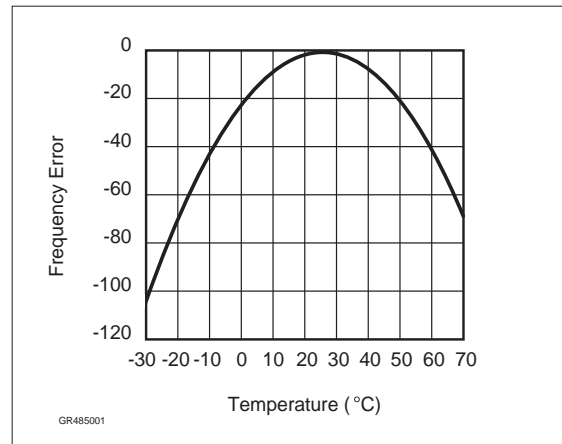


Figure 3. Frequency Error

ister is set to a 1, and the oscillator is running at exactly 32,768 Hz, the LSB of the seconds register toggles at 512 Hz. Any deviation from 512 Hz indicates the degree and direction of oscillator frequency shift at the test temperature. For example, a reading of 512.01024 Hz indicates a  $(1E6 * 0.01024) / 512$  or +20 ppm oscillator frequency error, requiring ten steps of negative calibration ( $10 * -2.034$  or -20.34) or 001010 to be loaded into the calibration byte for correction. To read the test frequency, the bq4850Y must be selected and held in an extended read of the seconds register, location 7FFF9, without having the read bit set. The frequency appears on DQ0. The FTE bit must be set using the write bit control. The FTE bit must be reset to 0 for normal clock operation to resume.

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### Absolute Maximum Ratings

Symbol	Parameter	Value	Unit	Conditions
V <sub>CC</sub>	DC voltage applied on V <sub>CC</sub> relative to V <sub>SS</sub>	-0.3 to 7.0	V	
V <sub>T</sub>	DC voltage applied on any pin excluding V <sub>CC</sub> relative to V <sub>SS</sub>	-0.3 to 7.0	V	V <sub>T</sub> ≤ V <sub>CC</sub> + 0.3
T <sub>OPR</sub>	Operating temperature	0 to +70	°C	
T <sub>STG</sub>	Storage temperature (V <sub>CC</sub> off; oscillator off)	-40 to +70	°C	
T <sub>BIAS</sub>	Temperature under bias	-10 to +70	°C	
T <sub>SOLDER</sub>	Soldering temperature	+260	°C	For 10 seconds

**Note:** Permanent device damage may occur if **Absolute Maximum Ratings** are exceeded. Functional operation should be limited to the Recommended DC Operating Conditions detailed in this data sheet. Exposure to conditions beyond the operational limits for extended periods of time may affect device reliability.

### Recommended DC Operating Conditions (T<sub>A</sub> = T<sub>OPR</sub>)

Symbol	Parameter	Minimum	Typical	Maximum	Unit	Notes
V <sub>CC</sub>	Supply voltage	4.5	5.0	5.5	V	
V <sub>SS</sub>	Supply voltage	0	0	0	V	
V <sub>IL</sub>	Input low voltage	-0.3	-	0.8	V	
V <sub>IH</sub>	Input high voltage	2.2	-	V <sub>CC</sub> + 0.3	V	

**Note:** Typical values indicate operation at T<sub>A</sub> = 25°C.

**DC Electrical Characteristics** ( $T_A = T_{OPR}$ ,  $V_{CCmin} \leq V_{CC} \leq V_{CCmax}$ )

Symbol	Parameter	Minimum	Typical	Maximum	Unit	Conditions/Notes
$I_{LI}$	Input leakage current	-	-	$\pm 1$	$\mu A$	$V_{IN} = V_{SS}$ to $V_{CC}$
$I_{LO}$	Output leakage current	-	-	$\pm 1$	$\mu A$	$\overline{CE} = V_{IH}$ or $\overline{OE} = V_{IH}$ or $\overline{WE} = V_{IL}$
$V_{OH}$	Output high voltage	2.4	-	-	V	$I_{OH} = -1.0$ mA
$V_{OL}$	Output low voltage	-	-	0.4	V	$I_{OL} = 2.1$ mA
$I_{SB1}$	Standby supply current	-	3	5	mA	$\overline{CE} = V_{IH}$
$I_{SB2}$	Standby supply current	-	0.1	1	mA	$\overline{CE} \geq V_{CC} - 0.2V$ , $0V \leq V_{IN} \leq 0.2V$ , or $V_{IN} \geq V_{CC} - 0.2V$
$I_{CC}$	Operating supply current	-	-	90	mA	Min. cycle, duty = 100%, $\overline{CE} = V_{IL}$ , $I_{I/O} = 0$ mA
$V_{PFD}$	Power-fail-detect voltage	4.30	4.37	4.50	V	
$V_{SO}$	Supply switch-over voltage	-	3	-	V	

**Note:** Typical values indicate operation at  $T_A = 25^\circ C$ ,  $V_{CC} = 5V$ .

**Capacitance** ( $T_A = 25^\circ C$ ,  $F = 1MHz$ ,  $V_{CC} = 5.0V$ )

Symbol	Parameter	Minimum	Typical	Maximum	Unit	Conditions
$C_{I/O}$	Input/output capacitance	-	-	10	pF	Output voltage = 0V
$C_{IN}$	Input capacitance	-	-	10	pF	Input voltage = 0V

**Note:** These parameters are sampled and not 100% tested.

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## AC Test Conditions

Parameter	Test Conditions
Input pulse levels	0V to 3.0V
Input rise and fall times	5 ns
Input and output timing reference levels	1.5 V (unless otherwise specified)
Output load (including scope and jig)	See Figures 4 and 5

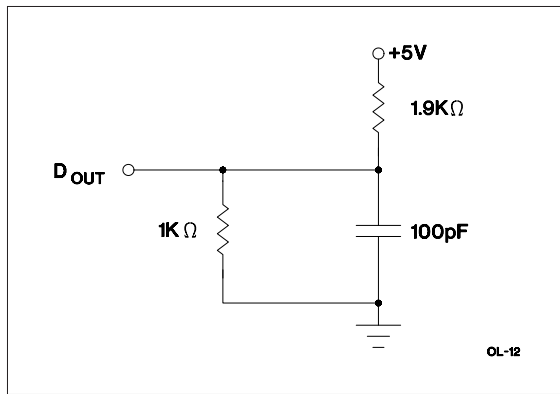


Figure 4. Output Load A

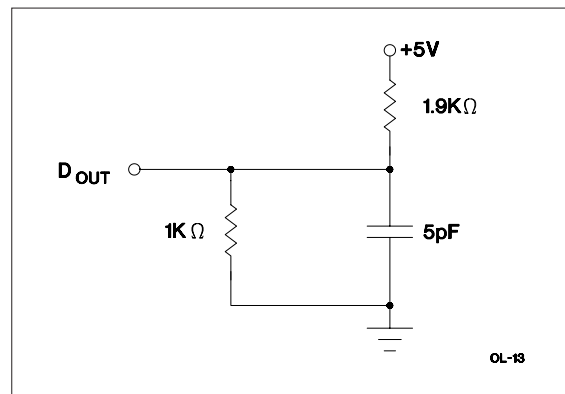


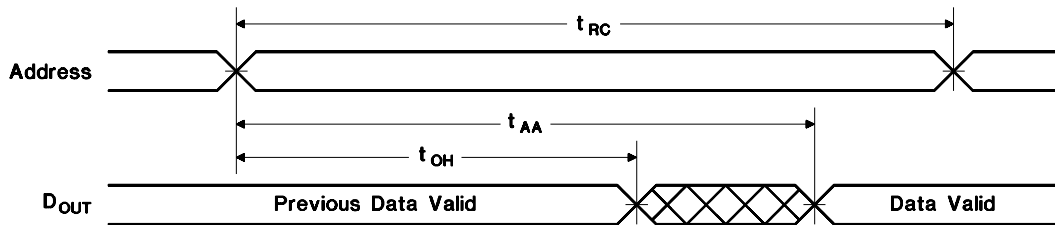
Figure 5. Output Load B

## Read Cycle ( $T_A = T_{OPR}, V_{CCmin} \leq V_{CC} \leq V_{CCMAX}$ )

Symbol	Parameter	-85		Unit	Conditions
		Min.	Max.		
$t_{RC}$	Read cycle time	85	-	ns	
$t_{AA}$	Address access time	-	85	ns	Output load A
$t_{ACE}$	Chip enable access time	-	85	ns	Output load A
$t_{OE}$	Output enable to output valid	-	45	ns	Output load A
$t_{CLZ}$	Chip enable to output in low Z	5	-	ns	Output load B
$t_{OLZ}$	Output enable to output in low Z	0	-	ns	Output load B
$t_{CHZ}$	Chip disable to output in high Z	0	35	ns	Output load B
$t_{OHZ}$	Output disable to output in high Z	0	25	ns	Output load B
$t_{OH}$	Output hold from address change	10	-	ns	Output load A

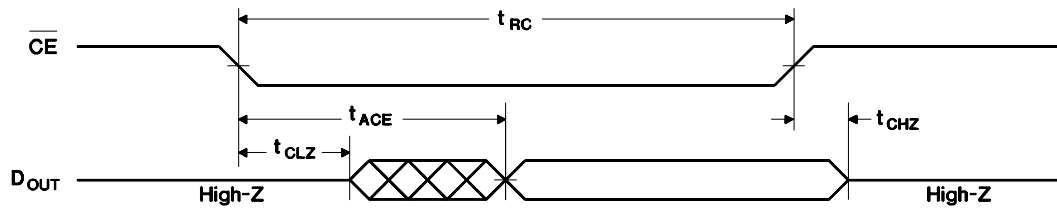


Read Cycle No. 1 (Address Access) <sup>1,2</sup>



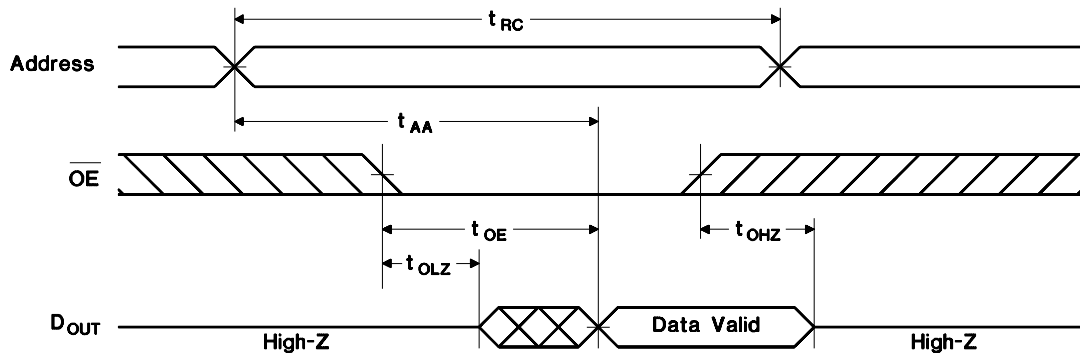
RC-1

Read Cycle No. 2 (CE Access) <sup>1,3,4</sup>



RC-2

Read Cycle No. 3 (OE Access) <sup>1,5</sup>



RC-3

- Notes:**
1.  $\overline{WE}$  is held high for a read cycle.
  2. Device is continuously selected:  $\overline{CE} = \overline{OE} = V_{IL}$ .
  3. Address is valid prior to or coincident with  $\overline{CE}$  transition low.
  4.  $\overline{OE} = V_{IL}$ .
  5. Device is continuously selected:  $\overline{CE} = V_{IL}$ .

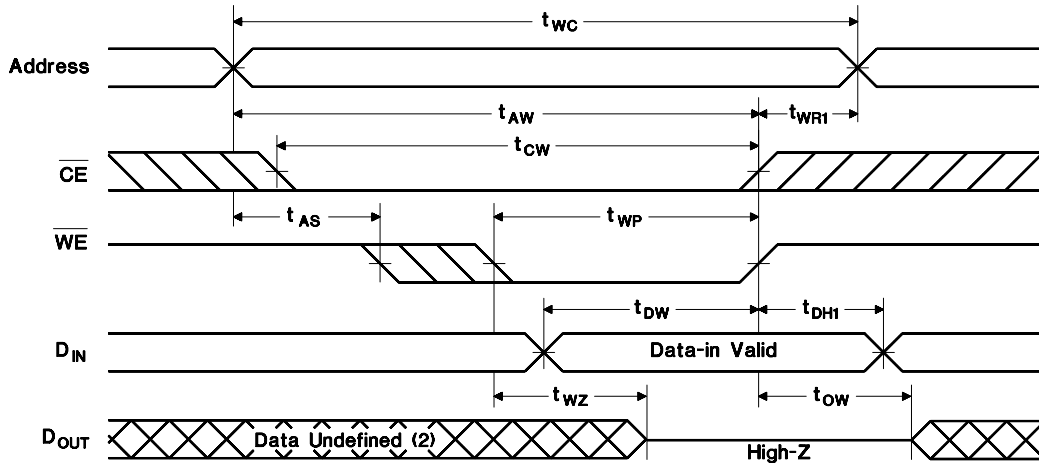
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### Write Cycle ( $T_A = T_{OPR}$ , $V_{CCMIN} \leq V_{CC} \leq V_{CCMAX}$ )

Symbol	Parameter	-85		Units	Conditions/Notes
		Min.	Max.		
t <sub>WC</sub>	Write cycle time	85	-	ns	
t <sub>CW</sub>	Chip enable to end of write	75	-	ns	(1)
t <sub>AW</sub>	Address valid to end of write	75	-	ns	(1)
t <sub>AS</sub>	Address setup time	0	-	ns	Measured from address valid to beginning of write. (2)
t <sub>WP</sub>	Write pulse width	65	-	ns	Measured from beginning of write to end of write. (1)
t <sub>WR1</sub>	Write recovery time (write cycle 1)	5	-	ns	Measured from $\overline{WE}$ going high to end of write cycle. (3)
t <sub>WR2</sub>	Write recovery time (write cycle 2)	15	-	ns	Measured from $\overline{CE}$ going high to end of write cycle. (3)
t <sub>DW</sub>	Data valid to end of write	35	-	ns	Measured to first low-to-high transition of either $\overline{CE}$ or $\overline{WE}$ .
t <sub>DH1</sub>	Data hold time (write cycle 1)	0	-	ns	Measured from $\overline{WE}$ going high to end of write cycle. (4)
t <sub>DH2</sub>	Data hold time (write cycle 2)	10	-	ns	Measured from $\overline{CE}$ going high to end of write cycle. (4)
t <sub>WZ</sub>	Write enabled to output in high Z	0	30	ns	I/O pins are in output state. (5)
t <sub>OW</sub>	Output active from end of write	0	-	ns	I/O pins are in output state. (5)

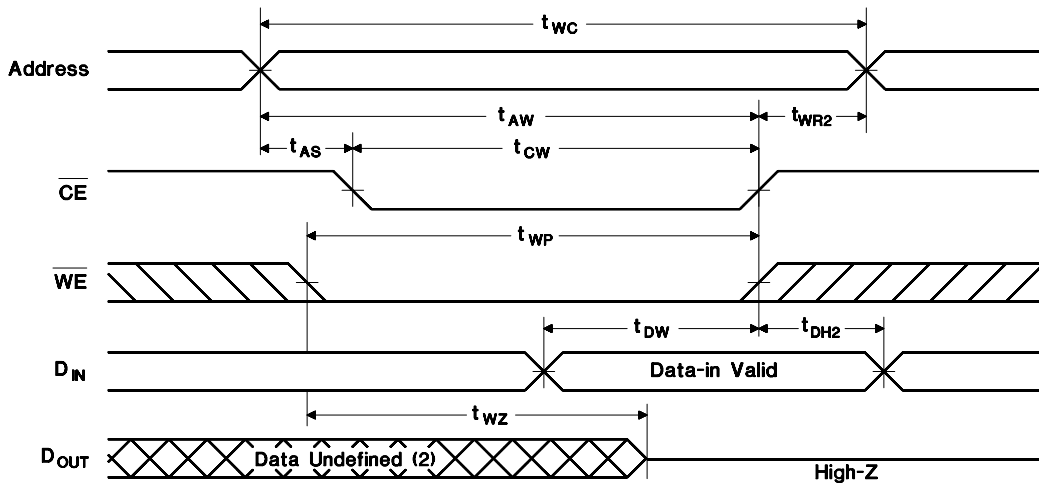
- Notes:**
1. A write ends at the earlier transition of  $\overline{CE}$  going high and  $\overline{WE}$  going high.
  2. A write occurs during the overlap of a low  $\overline{CE}$  and a low  $\overline{WE}$ . A write begins at the later transition of  $\overline{CE}$  going low and  $\overline{WE}$  going low.
  3. Either t<sub>WR1</sub> or t<sub>WR2</sub> must be met.
  4. Either t<sub>DH1</sub> or t<sub>DH2</sub> must be met.
  5. If  $\overline{CE}$  goes low simultaneously with  $\overline{WE}$  going low or after  $\overline{WE}$  going low, the outputs remain in high-impedance state.

**Write Cycle No. 1 (WE-Controlled)** <sup>1,2,3</sup>



WC-14

**Write Cycle No. 2 (CE-Controlled)** <sup>1,2,3,4,5</sup>



WC-15

- Notes:**
1.  $\overline{CE}$  or  $\overline{WE}$  must be high during address transition.
  2. Because I/O may be active ( $\overline{OE}$  low) during this period, data input signals of opposite polarity to the outputs must not be applied.
  3. If  $\overline{OE}$  is high, the I/O pins remain in a state of high impedance.
  4. Either  $t_{WR1}$  or  $t_{WR2}$  must be met.
  5. Either  $t_{DH1}$  or  $t_{DH2}$  must be met.

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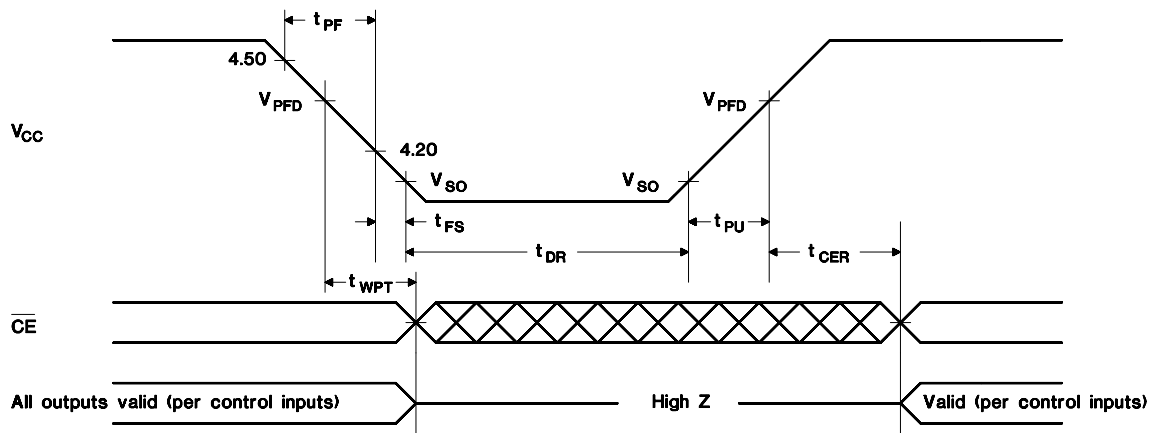
## Power-Down/Power-Up Cycle ( $T_A = T_{OPR}$ )

Symbol	Parameter	Minimum	Typical	Maximum	Unit	Conditions
$t_{PF}$	$V_{CC}$ slew, 4.50 to 4.20 V	300	-	-	$\mu\text{s}$	
$t_{FS}$	$V_{CC}$ slew, 4.20 to $V_{SO}$	10	-	-	$\mu\text{s}$	
$t_{PU}$	$V_{CC}$ slew, $V_{SO}$ to $V_{PFD}$ (max.)	0	-	-	$\mu\text{s}$	
$t_{CER}$	Chip enable recovery time	40	100	200	ms	Time during which SRAM is write-protected after $V_{CC}$ passes $V_{PFD}$ on power-up.
$t_{DR}$	Data-retention time in absence of $V_{CC}$	10	-	-	years	$T_A = 25^\circ\text{C}$ . (2)
$t_{WPT}$	Write-protect time	40	100	160	$\mu\text{s}$	Delay after $V_{CC}$ slews down past $V_{PFD}$ before SRAM is write-protected.

- Notes:**
1. Typical values indicate operation at  $T_A = 25^\circ\text{C}$ ,  $V_{CC} = 5\text{V}$ .
  2. Battery is disconnected from circuit until after  $V_{CC}$  is applied for the first time.  $t_{DR}$  is the accumulated time in absence of power beginning when power is first applied to the device.

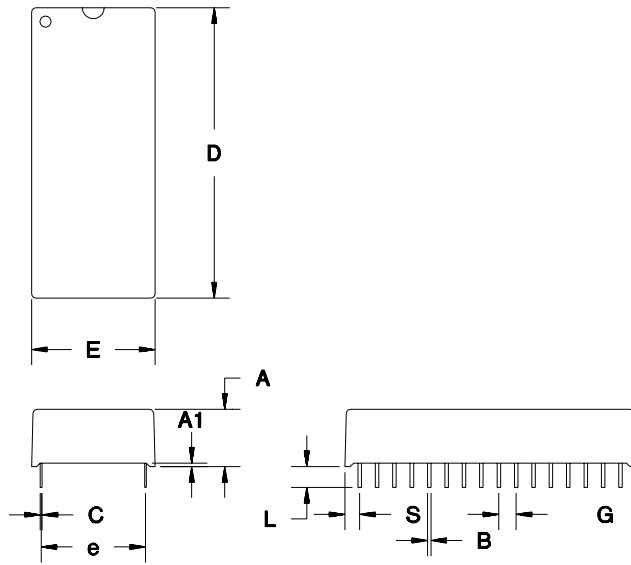
**Caution:** Negative undershoots below the absolute maximum rating of  $-0.3\text{V}$  in battery-backup mode may affect data integrity.

## Power-Down/Power-Up Timing



PD-16

MA: 32-Pin A-Type Module



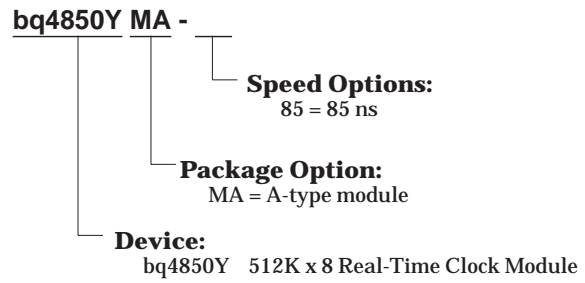
32-Pin MA (A-Type Module)

Dimension	Inches		Millimeters	
	Min.	Max.	Min.	Max.
A	0.365	0.375	9.27	9.53
A1	0.015	-	0.38	-
B	0.017	0.023	0.43	0.58
C	0.008	0.013	0.20	0.33
D	1.670	1.700	42.42	43.18
E	0.710	0.740	18.03	18.80
e	0.590	0.630	14.99	16.00
G	0.090	0.110	2.29	2.79
L	0.120	0.150	3.05	3.81
S	0.075	0.110	1.91	2.79

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## Ordering Information





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